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Hamiltonian of graphene**

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GEOMETRIC MULTIGRID FOR THE TIGHT-BINDING HAMILTONIAN OF GRAPHENE

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Abstract. In order to calculate the electronic properties of graphene structures a tight-binding approach can be used. The tight-binding formulation leads to linear systems of equations which are maximally indefinite and can be seen both as a discretization of a system of PDEs or a staggered discretization. In this paper we develop a geometric multigrid method for this problem and undertake a complete two-level convergence analysis using local Fourier analysis. In numerical tests we show the scalability of the resulting multigrid method with respect to various geometric parameters.

Key words. geometric multigrid, indefinite operators, local Fourier analysis, staggered triangular grid, honeycomb lattice, tight-binding Hamiltonian, Graphene

AMS subject classifications. 65F10, 65N55, 65Z05

1. Introduction. In this paper we construct a well behaving geometric multigrid algorithm for a maximally indefinite (and for certain geometries even singular) linear system of equations. By using local Fourier analysis (LFA) we prove the convergence of the two-grid method.

The maximally indefinite system arises from the tight-binding approach for electronic structure calculations of graphene [10, 11, 19], which plays a key-role in computationally demanding simulations, such as Monte-Carlo studies [9, 22]. Herein, the indefinite operator is formulated on a honeycomb lattice which can be interpreted as a staggered triangular lattice.

Multigrid methods for indefinite problems have been considered mainly in the context of the indefinite Helmholtz equation or other 2nd order elliptic boundary value problems. Typically, convergence of a multigrid method for these problems can only be guaranteed if particular conditions are fulfilled; cf. [1, 2, 5, 6, 20, 23]. The most prominent restriction oftentimes requires that the coarsest grid needs to be sufficiently fine/large. This means that there is no such method with the typical multigrid advantage—an asymptotic convergence rate independent of the grid size. Recently, in the context of Lattice Gauge Theory algebraic multigrid methods have experimentally been shown to be efficient for indefinite spin systems in [12, 16, 18]. However no theoretical proof of convergence is available for these methods.

LFA was introduced in [7, 8] and is known as a powerful tool for the convergence analysis of multigrid methods. A comprehensive introduction to LFA on rectangular grids can be found in [21]. The concept has been further developed to other triangular and hexagonal grids in [13, 24] and to systems of PDEs, e.g. curl-curl and Navier-Stokes, in [4, 17, 21]. In the LFA for the curl-curl equation, the PDE is discretized by first order edge elements on a regular quadrilateral grid such that the unknowns correspond to the edges of the grid. Since the edges in vertical direction are different from the edges in horizontal direction, the system and the LFA is treated as a staggered rectangular lattice which is very similar to the case discussed in here.

The remainder of this paper is organized as follows. First, we give an introduction about the geometric structure of graphene and the geometry of the graphene patches

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which are considered in this paper. Then we introduce the tight-binding Hamiltonian of graphene in its most general form and show how the spectrum of this operator can be extracted analytically. Afterwards, we sketch roughly the concept of multigrid methods and explain our construction in detail. At this point, the previously obtained spectral information of the operator is of crucial importance. The LFA which proves the convergence for the complete two-grid method is given right after. In the last section, numerical results are presented and compared to the results of the LFA. These results show the scalability of the twogrid and multigrid method with respect to several geometric parameters.

2. Graphene. Carbon materials occur in many different allotropes. Besides the well-known forms of graphite and diamond, reseachers recently isolated graphene, a single layer of carbon atoms bonded in a hexagonal or "honeycomb" structure. The distance a of two neighboring carbon atoms in graphene is approximately 1.42\AA . Graphene is the basic element of fullerenes, which are molecules of carbons in the form of a sphere (Buckminsterfullerene C_{60}), tubes (carbon nanotubes) and many other shapes [10, 14]. In this paper we restrict ourselves to rectangular graphene sheets with different boundary conditions, which means we are dealing with sheets, tubes and tori. In order to describe these geometries in more detail, we first introduce notation for lattice structures and show how the hexagonal structure of graphene can be viewed as a triangular lattice with two atoms per lattice site.

DEFINITION 1. A 2-dimensional lattice generated by the vectors $a_1, a_2 \in \mathbb{R}^2$ is given by

$$\mathbb{L} := \{x \in \mathbb{R}^2 \mid x = z_1 a_1 + z_2 a_2, \quad z_1, z_2 \in \mathbb{Z}\}.$$

While the hexagonal structure of graphene is not a lattice per se it can be interpreted as a triangular lattice \mathbb{L}_T of pairs of atoms generated by the vectors

$$(1) \quad a_1 = \left(\frac{3a}{2}, \frac{\sqrt{3}a}{2}\right), \quad a_2 = \left(\frac{3a}{2}, -\frac{\sqrt{3}a}{2}\right)$$

as illustrated in Figure 1. The graphene lattice is then given by the set of points

$$(2) \quad \mathbb{L}_G := \{x + \delta\tau, \quad x \in \mathbb{L}_T, \delta \in \{0, 1\}\}$$

with $\tau := (a, 0)$. To distinguish the points we denote $x \in \mathbb{L}_T$ by type A and $x \in \mathbb{L}_G \setminus \mathbb{L}_T$ by type B .

DEFINITION 2. Define a rectangular graphene patch $\mathbb{G}_{n,m,\ell}$ with $n, m, \ell \in \mathbb{N}$ by

$$\mathbb{G}_{n,m,\ell} := \mathbb{L}_G \cap R,$$

where $R := \{x \in \mathbb{R}^2 : x = \alpha_1 C + \alpha_2 T, \alpha_i \in (0, 1]\}$. In here the boundary vectors of the confining rectangle R are given by

$$C = na_1 + ma_2 \quad \text{and} \quad T = \ell \left(\frac{2m+n}{N_r} a_1 - \frac{2n+m}{N_r} a_2 \right),$$

where $N_r = \gcd(2n+m, 2m+n)$ ¹. Its chiral angle is given by $\theta = -\frac{\pi}{6} + \tan^{-1}\left(\frac{\sqrt{3}m}{m+2n}\right)$. One easily checks that T is indeed orthogonal to C ; cf. Figure 2.

¹ $\gcd(a, b)$ is the greatest common divisor of $a, b \in \mathbb{N}$

DEFINITION 5. Let \mathbb{L} be a 2-dimensional lattice generated by the vectors a_1 and a_2 . Then its reciprocal lattice is defined by vectors b_1 and b_2 such that

$$\langle b_i, a_j \rangle_2 = 2\pi \cdot \delta_{ij}.$$

The reciprocal lattice of \mathbb{L}_T is defined by the basis vectors

$$b_1 = \frac{2\pi}{3a} \left(1, \sqrt{3} \right), \quad b_2 = \frac{2\pi}{3a} \left(1, -\sqrt{3} \right).$$

For a local Fourier analysis it is sufficient to consider a finite area of the reciprocal lattice due to the periodicity of the Fourier modes, i.e.,

$$e^{i\langle k_1 b_1 + k_2 b_2, x \rangle_2} = 1, \quad k_1, k_2 \in \mathbb{Z}^2, x \in \mathbb{L}_T.$$

For example the parallelogram \mathbb{D}_G spanned by the vectors b_1 and b_2 , i.e.,

$$\mathbb{D}_G = \{k_1 b_1 + k_2 b_2, 0 \leq k_1, k_2 < 1\}.$$

In the context of solid state physics, it is more common to consider the *first Brillouin zone*, also known as the Wigner-Seitz cell or Voronoi cell of the reciprocal lattice, illustrated in [Figure 5](#).

The spectrum of a locally defined operator on an infinite lattice can be computed using Bloch's theorem [3], which states that the eigenfunctions of an operator defined on a lattice are given by

$$\Psi(k, x) = e^{i\langle k, x \rangle_2} u(x),$$

where $k = k_1 b_1 + k_2 b_2, 0 \leq k_1, k_2 < 1, x \in \mathbb{L}$ and $u(x)$ is periodic on \mathbb{L} , i.e., $u(x + z_1 a_1 + z_2 a_2) = u(x), z_1, z_2 \in \mathbb{Z}$. With respect to the tight binding Hamiltonian of graphene we thus find the following description of its spectrum on an infinite lattice (shown in [Figure 6](#)).

THEOREM 6. *The eigenvalues of $A_{[0, t_1]}$ are given by*

$$(5) \quad E(k) = \pm t_1 \sqrt{3 + 2 \cos(\langle k, a_1 \rangle_2) + 2 \cos(\langle k, a_2 \rangle_2) + 2 \cos(\langle k, a_2 - a_1 \rangle_2)},$$

with corresponding eigenfunctions

$$\widehat{\Psi}(k, x) = \alpha_k^{(1)} \begin{pmatrix} \Psi(k, x) \\ \Psi(k, x + \tau) \end{pmatrix} + \alpha_k^{(2)} \begin{pmatrix} \Psi(k, x) \\ -\Psi(k, x + \tau) \end{pmatrix},$$

where $\Psi(k, x) = e^{i\langle k, x \rangle_2}, k \in \mathbb{D}_G$ and $x \in \mathbb{L}_T$.

Proof. We have

$$\begin{aligned} A_{[0, t_1]} \begin{pmatrix} \Psi(k, x) \\ \pm \Psi(k, x + \tau) \end{pmatrix} &= t_1 \begin{pmatrix} \Psi(k, x + \tau) + \Psi(k, x - a_1 + \tau) + \Psi(k, x - a_2 + \tau) \\ \pm [\Psi(k, x) + \Psi(k, x + a_1) + \Psi(k, x + a_2)] \end{pmatrix} \\ &= t_1 \begin{pmatrix} (1 + e^{-i\langle k, a_1 \rangle_2} + e^{-i\langle k, a_2 \rangle_2}) \Psi(k, x + \tau) \\ \pm (1 + e^{i\langle k, a_1 \rangle_2} + e^{i\langle k, a_2 \rangle_2}) \Psi(k, x) \end{pmatrix}. \end{aligned}$$

Thus we obtain the eigenvalues of the tight-binding Hamiltonian by diagonalizing the hermitian 2×2 matrix

$$(6) \quad \begin{pmatrix} 0 & 1 + e^{i\langle k, a_1 \rangle_2} + e^{i\langle k, a_2 \rangle_2} \\ 1 + e^{-i\langle k, a_1 \rangle_2} + e^{-i\langle k, a_2 \rangle_2} & 0 \end{pmatrix}. \quad \square$$

REMARK 7. The zeroes of $E(k)$ from (5) are called Dirac points [10]. The two Dirac points in \mathbb{D}_G are given by

$$K_1 = \frac{1}{3}b_1 + \frac{2}{3}b_2 \quad \text{and} \quad K_2 = \frac{2}{3}b_1 + \frac{1}{3}b_2,$$

which can easily be checked by analyzing the real and imaginary part of the entries in (6) separately.

A corresponding basis of the kernel is then given by

$$(7) \quad \begin{pmatrix} e^{i\langle K_1, x \rangle_2} \\ e^{i\langle K_1, x+\tau \rangle_2} \end{pmatrix}, \begin{pmatrix} e^{i\langle K_1, x \rangle_2} \\ -e^{i\langle K_1, x+\tau \rangle_2} \end{pmatrix}, \begin{pmatrix} e^{i\langle K_2, x \rangle_2} \\ e^{i\langle K_2, x+\tau \rangle_2} \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} e^{i\langle K_2, x \rangle_2} \\ -e^{i\langle K_2, x+\tau \rangle_2} \end{pmatrix}, x \in \mathbb{L}_T.$$

Note, that the points $K_i - \delta(b_j + \gamma b_i)$, $i, j = 1, 2$, $\delta, \gamma = 0, 1$ are the six vertices of the first Brillouin zone as illustrated in Figure 5.

The remainder of the paper deals with the treatment of the tight-binding Hamiltonian on finite sections of the graphene lattice. Typical boundary conditions for the rectangular graphene sheets $\mathbb{G}_{n,m,\ell}$ are *open* and *periodic*. Open boundary conditions are realized by simply omitting the terms of the operator which would belong to off-lattice points in (4). Periodic boundary conditions are defined by translation equalities of the kind

$$(8) \quad x + C = x \quad \text{and} \quad x + T = x \quad \text{for all } x \in \mathbb{G}_{n,m,\ell}.$$

LEMMA 8. The eigenvalues of the tight-binding Hamiltonian $A_{[0,t_1]}$ on a periodic rectangular graphene sheet $\mathbb{G}_{n,m,\ell}$ are given by

$$E(k) = \pm t_1 \sqrt{3 + 2 \cos(\langle k, a_1 \rangle_2) + 2 \cos(\langle k, a_2 \rangle_2) + 2 \cos(\langle k, a_2 - a_1 \rangle_2)},$$

where k is restricted to the discrete set $\Lambda_{n,m,\ell} \cap \mathbb{D}_G$ with

$$\Lambda_{n,m,\ell} := \left\{ \frac{1}{2(n^2 + nm + m^2)} (z_1 \hat{a}_1 + z_2 \hat{a}_2), \quad z_1, z_2 \in \mathbb{Z} \right\}$$

where the basis vectors are given by

$$\hat{a}_1 = \frac{n \cdot N_r}{\ell} b_1 - \frac{m \cdot N_r}{\ell} b_2 \quad \text{and} \quad \hat{a}_2 = (2m + n)b_1 + (2n + m)b_2.$$

Thus $K_1, K_2 \in \Lambda_{n,m,\ell}$ iff

$$(n - m) \bmod 3 = 0, \quad \ell \cdot m \bmod N_r = 0, \quad \ell \cdot n \bmod N_r = 0.$$

Proof. Using the identity translations (8) one can show that the eigenfunctions with $k \in \Lambda_{n,m,\ell}$ are well defined. Further, due to $|\mathbb{G}_{n,m,\ell}| = 2|\Lambda_{n,m,\ell} \cap \mathbb{D}_G|$ (cf. (3)) there cannot be any other eigenfunctions. The statement about the Dirac points K_1, K_2 is a direct consequence. \square

REMARK 9. Both Theorem 6 and Lemma 8 can be generalized to arbitrary tight-binding Hamiltonians $A_{[t_0, t_1, t_2, \dots, t_M]}$. Using the specified lattice Fourier modes the operator is again block diagonalized into 2×2 blocks.

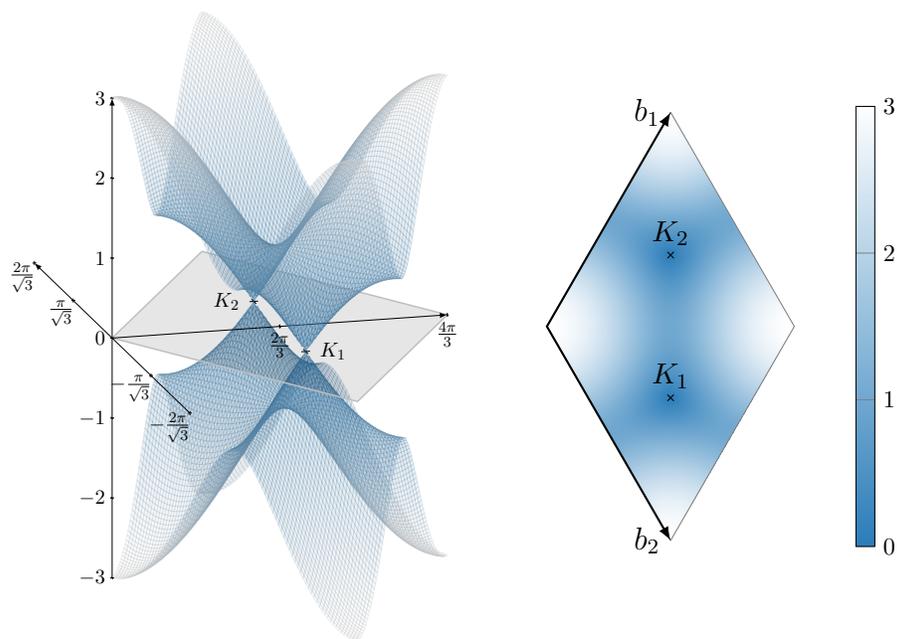


Figure 6: Spectrum of $A_{[0,-1]}$, i.e., $E(k), k \in \mathbb{D}_G$

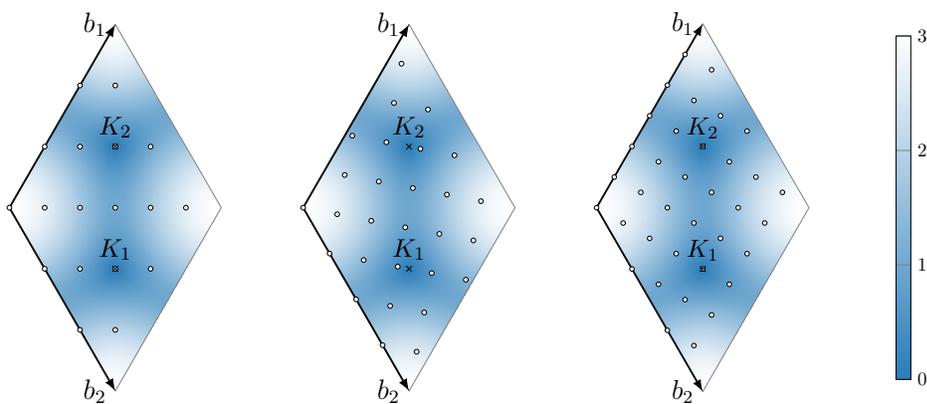


Figure 7: Discrete spectrum $\Lambda_{n,m,\ell}$ of $A_{[0,-1]}$ for different choices of (n, m, ℓ) . Left $(3, 3, 3)$, middle $(4, 2, 1)$, right $(6, 0, 3)$.

3. Multigrid. Multigrid methods are iterative solvers for linear systems of equations $Ax = b, A \in \mathbb{R}^{n \times n}$ that exploit the geometric structure of the problem, such that in contrast to other iterative methods a convergence rate independent of the mesh size can be achieved. A multigrid method relies on the efficient interplay between a *smoother*, S , which typically is a simple stationary iterative scheme, and a coarse grid correction that is able to treat error components untouched by the smoother on a coarser scale. In order to formulate the coarse grid correction one first has to specify suitable coarse degrees of freedom. Oftentimes this corresponds to a splitting of the

lattice points \mathbb{L}_G of the current level into variables which are used on the coarse grid as well, \mathbb{L}_G^c , and the remainder \mathbb{L}_G^f . Once the choice of coarse degrees of freedom has been made, appropriate *interpolation* and *restriction* operators need to be defined

$$P : \mathbb{R}^{n_c} \rightarrow \mathbb{R}^n \quad \text{and} \quad R : \mathbb{R}^n \rightarrow \mathbb{R}^{n_c},$$

where n_c denotes the number of coarse degrees of freedom, e.g., $n_c = |\mathbb{L}_G^c|$. The coarse grid correction is then defined by its error propagator

$$I - P(RAP)^{-1}RA,$$

assuming that RAP is non-singular. In case A is symmetric the restriction R is typically chosen as P^T , which results in a Galerkin coarse grid correction. In [Algorithm 1](#) we give a pseudo-code of the resulting two grid method. The (V-cycle) multigrid method is obtained by replacing $(RAP)^{-1}$ by (a single iteration of) yet another two grid method [21]. Note, that for the recursive applicability of the two grid construction on the coarse grid problem RAP one has to make sure that key features of A are preserved.

In what follows we specify the multigrid components for the graphene tight-binding Hamiltonian in more detail before we analyze the convergence of the resulting method in [section 4](#).

Algorithm 1 Tentative two grid method

- 1: Given an initial guess $x^{(0)}$, $r^{(0)} = b - Ax^{(0)}$
 - 2: **for all** $m = 1, 2, \dots$ **do**
 - 3: $x^{(m)} = S^{\nu_1}(A, x^{(m-1)}, b)$ ▷ pre-smooth ν_1 times
 - 4: $r_c = P^H(b - Ax^{(m)})$ ▷ coarsen the residual
 - 5: $A_c x_c = r_c$ ▷ solve the coarse grid problem
 - 6: $x^{(m)} = x^{(m)} + Px_c$ ▷ interpolate and correct
 - 7: $x^{(m)} = S^{\nu_2}(A, x^{(m)}, b)$ ▷ post-smooth ν_2 times
 - 8: **end for**
-

Smoother. The smoother for our multigrid method is the Kaczmarz iteration [15], which can be viewed as the Gauss-Seidel iteration on the normal equations $A^T A x = A^T b$. Given a splitting of $A^T A$ into its diagonal and triangular parts

$$(9) \quad A^T A = D + L + U,$$

the Kaczmarz iteration can be written as

$$x \leftarrow x + (D + L)^{-1}(A^T(b - Ax)).$$

Note that the Kaczmarz iteration depends on the ordering of the unknowns. In here we use a lexicographic ordering as depicted in [Figure 8](#). That is, we assume that the lattice points are numbered from bottom to top and left to right.

Coarse lattice points. We choose the splitting of lattice points $\mathbb{L}_G = \mathbb{L}_G^c \cup \mathbb{L}_G^f$ into coarse and fine lattice points in a way that guarantees the recursive applicability of the coarse grid construction. That is, the set of coarse grid lattice points should again be a honeycomb lattice.

We achieve this by defining a coarse triangular lattice

$$\mathbb{L}_T^c := \{\tau + z_1 \cdot 2a_1 + z_2 \cdot 2a_2, z_1, z_2 \in \mathbb{Z}\}.$$

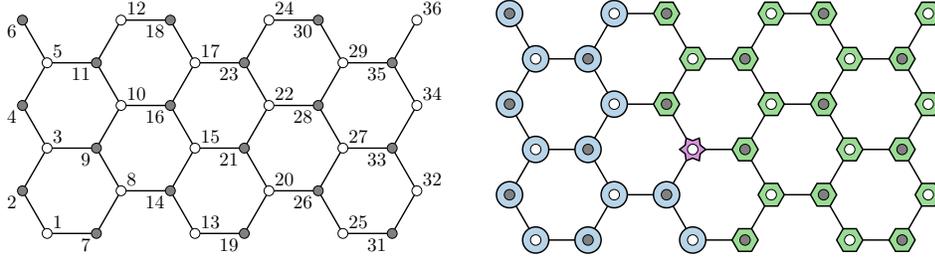


Figure 8: Lexicographic ordering of the graphene lattice (left) and status of unknowns within a Kaczmarz iteration (right). Unknowns already updated \circ ; current unknown to be updated \star ; remaining unknowns not yet updated \circ .

The corresponding coarse honeycomb lattice \mathbb{L}_G^c is then given by

$$\mathbb{L}_G^c := \{x + \delta \cdot 2\tau, x \in \mathbb{L}_T^c, \delta \in \{0, 1\}\}.$$

The coarse lattice points are identified by having a coarse lattice point located on the opposite site of any of the adjacent hexagons; cf. Figure 9. Using the same naming convention as in section 2 for the coarse lattice points, we denote $x \in \mathbb{L}_T^c$ by type A^c and $x \in \mathbb{L}_G^c \setminus \mathbb{L}_T^c$ by type B^c . Thus type A^c (B^c) lattice points are of type B (A) on the fine lattice.

Defining sublattices

$$(10) \quad \mathbb{L}_T^{(\zeta_1, \zeta_2)} := \{x + \zeta_1 a_1 + \zeta_2 a_2, x \in \mathbb{L}_T^c\},$$

with $\mathbb{L}_T^{(0,0)} = \mathbb{L}_T^c$, the fine lattice can be split into

$$\mathbb{L}_T = \bigcup_{(\zeta_1, \zeta_2) \in \{0,1\}^2} \mathbb{L}_T^{(\zeta_1, \zeta_2)}.$$

Given this splitting of \mathbb{L}_T one also obtains a splitting of \mathbb{L}_G by

$$(11) \quad \mathbb{L}_G^{(\zeta_1, \zeta_2)} := \{x + \delta 2\tau, x \in \mathbb{L}_T^{(\zeta_1, \zeta_2)}, \delta \in \{0, 1\}\}$$

as illustrated in Figure 10.

Intergrid transfer. Due to the fact that the tight-binding Hamiltonian of graphene results in a symmetric linear operator we choose to use a Galerkin construction, i.e., $R = P^T$, and thus can restrict the discussion to the construction of P . Given a splitting of the lattice points $\mathbb{L}_G = \mathbb{L}_G^c \cup \mathbb{L}_G^f$, the main idea in the construction of the interpolation operator

$$P : \mathbb{L}_G^c \rightarrow \mathbb{L}_G, \quad P|_{\mathbb{L}_G^c} = I$$

is the exact preservation of kernel modes of the tight-binding Hamiltonian. That is, we want the interpolation operator to interpolate the Fourier modes (7) corresponding to the Dirac points K_1, K_2 exactly in the following sense

$$(12) \quad \begin{pmatrix} e^{i\langle K_j, x \rangle_2} \\ \pm e^{i\langle K_j, x + \tau \rangle_2} \end{pmatrix} = P \begin{pmatrix} \pm e^{i\langle K_j, y \rangle_2} \\ e^{i\langle K_j, y + 2\tau \rangle_2} \end{pmatrix}, \quad j = 1, 2, \quad x \in \mathbb{L}_T, \quad y \in \mathbb{L}_T^c.$$

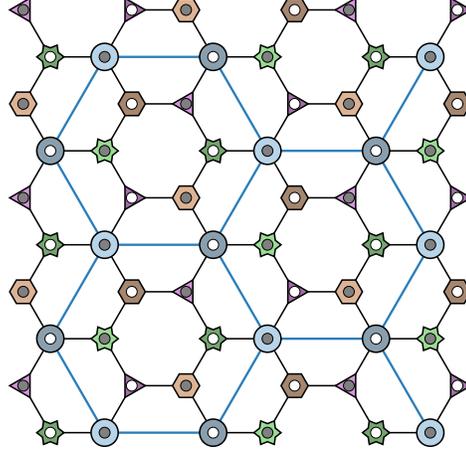
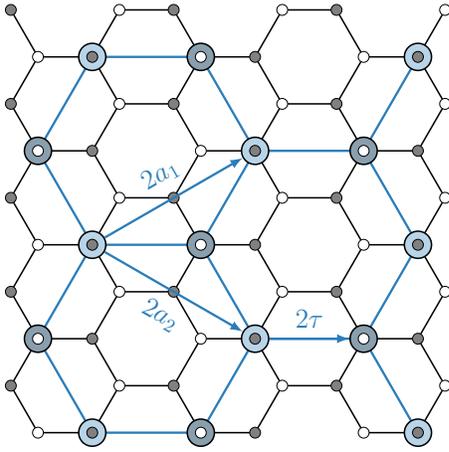


Figure 9: Coarse lattice $\mathbb{L}_G^c \subset \mathbb{L}_G$ and Figure 10: Splitting of \mathbb{L}_G into coarse lattice vectors of \mathbb{L}_T^c .
 $\circ/\bullet L_G^{(0,0)}$, $\blacktriangle/\blacktriangleright L_G^{(0,1)}$, $\hexagon/\hexagon L_G^{(1,0)}$ and $\star/\star L_G^{(1,1)}$.

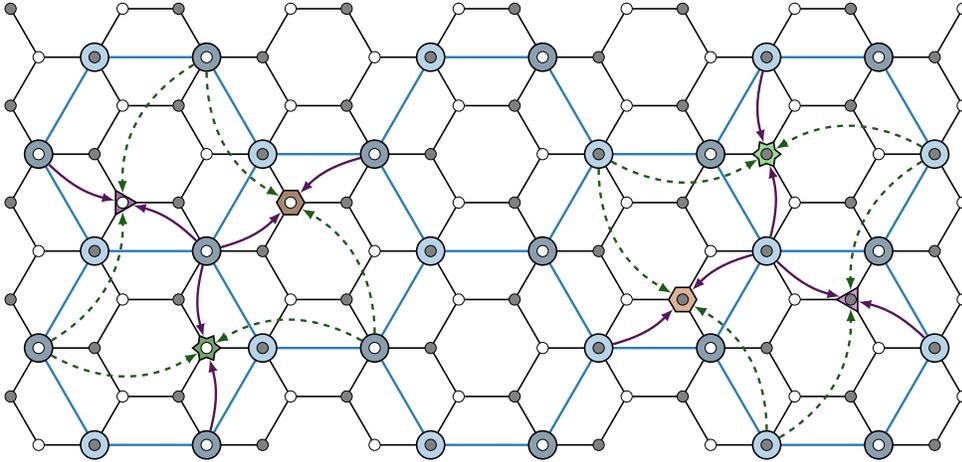


Figure 11: Illustration of interpolation using weights $\color{purple}\rightarrow w_s$ and $\color{green}-\!\!-\!\!-\rightarrow w_\ell$.

The problem of preserving these four modes can be reduced to a problem involving only two by choosing the interpolation points according to the species (either A or B) of the fine lattice point that is the target of interpolation. That is, a coarse lattice point of species A^c or B^c interpolates only to fine lattice points of species B or A , respectively. With this choice the \pm term cancels, which halves the number of modes to fit and thus it only requires the solution of the interpolation problem (12) for either species A or B .

In addition the interpolation points should consist of coarse lattice points in the vicinity of the fine lattice point. Even though two interpolation points would be sufficient to resolve (12) we opt to define four interpolation points for each lattice

Any operator X which is H_k -invariant for all k can then be expressed by a family of 8×8 Matrices $X_k : H_k \rightarrow H_k$, defined by

$$XV_k = X_k V_k,$$

where $V_k = (\varphi_{0,0}^+ \ \varphi_{0,0}^- \ \varphi_{0,1}^+ \ \varphi_{0,1}^- \ \varphi_{1,0}^+ \ \varphi_{1,0}^- \ \varphi_{1,1}^+ \ \varphi_{1,1}^-)^T$ is the (ordered) collection of the 8 harmonic functions corresponding to k .

The amplification factor of H at k is defined as $\rho(H_k) = \sqrt{\lambda_{\max}(H_k^T H_k)}$.

We now show that M is an H_k -invariant operator and give a product formula for M_k . We start with the analysis of the tight-binding operator $A_{[0,-1]}$.

LEMMA 11. Let $k = k_1 b_1 + k_2 b_2 \in \mathbb{D}_G$ with $k_1, k_2 \in [0, \frac{1}{2})$ and $A = A_{[0,-1]}$, then A is H_k -invariant and A_k is a block-diagonal matrix with four blocks $A_{\widehat{k}} \in \mathbb{R}^{2 \times 2}$, $\widehat{k} \in \{k + \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, (\xi_1, \xi_2) \in \{0, 1\}^2\}$ with

$$A_{\widehat{k}} = \begin{pmatrix} 0 & 1 + e^{i\langle \widehat{k}, a_1 \rangle_2} + e^{i\langle \widehat{k}, a_2 \rangle_2} \\ 1 + e^{-i\langle \widehat{k}, a_1 \rangle_2} + e^{-i\langle \widehat{k}, a_2 \rangle_2} & 0 \end{pmatrix}.$$

Proof. See Theorem 6. \square

LEMMA 12. Let $k = k_1 b_1 + k_2 b_2 \in \mathbb{D}_G$ with $k_1, k_2 \in [0, \frac{1}{2})$, $A = A_{[0,-1]}$, then the Kaczmarz smoother given by its error propagator

$$S = -(L + D)^{-1} U$$

based on the splitting (9) is H_k -invariant and, assuming lexicographic ordering, S_k is block-diagonal with four blocks $S_{\widehat{k}} \in \mathbb{R}^{2 \times 2}$ corresponding to $\widehat{k} \in \{k + \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, (\xi_1, \xi_2) \in \{0, 1\}^2\}$. Each block $S_{\widehat{k}}$ fulfills

$$S_{\widehat{k}} = \begin{pmatrix} -\frac{e^{i\langle \widehat{k}, a_1 \rangle_2} + e^{i\langle \widehat{k}, a_2 \rangle_2} + e^{i\langle \widehat{k}, a_1 - a_2 \rangle_2}}{3 + e^{i\langle \widehat{k}, -a_1 \rangle_2} + e^{i\langle \widehat{k}, -a_2 \rangle_2} + e^{i\langle \widehat{k}, -a_1 + a_2 \rangle_2}} & 0 \\ 0 & -\frac{e^{i\langle \widehat{k}, a_1 \rangle_2} + e^{i\langle \widehat{k}, a_2 \rangle_2} + e^{i\langle \widehat{k}, a_1 - a_2 \rangle_2}}{3 + e^{i\langle \widehat{k}, -a_1 \rangle_2} + e^{i\langle \widehat{k}, -a_2 \rangle_2} + e^{i\langle \widehat{k}, -a_1 + a_2 \rangle_2}} \end{pmatrix}.$$

Proof. This statement is a direct consequence of $A^T A = A_{[3,0,1]}$. \square

Concerning the coarse grid correction we first give an expression for the action of the restriction and interpolation. We introduce for each $k = k_1 b_1 + k_2 b_2 \in \mathbb{D}_G$ with $k_1, k_2 \in [0, \frac{1}{2})$ the space H_k^c by

$$H_k^c := \{\varphi_c^\pm(k, x) := \begin{pmatrix} \pm e^{i\langle k, x \rangle_2} \\ e^{i\langle k, x + 2\tau \rangle_2} \end{pmatrix}, x \in \mathbb{L}_T^c\}.$$

Analogously to V_k we define $V_k^c = (\varphi_c^+ \ \varphi_c^-)^T$.

LEMMA 13. Let $k = k_1 b_1 + k_2 b_2 \in \mathbb{D}_G$ with $k_1, k_2 \in [0, \frac{1}{2})$ the restriction operator P^T with interpolation weights w_s and w_ℓ maps $H_k \rightarrow H_k^c$. Thus it can be represented by $R_k \in \mathbb{C}^{2 \times 8}$ such that $RV_k = V_k^c R_k$. The 2×2 blocks of R_k , corresponding to $\widehat{k} = k + (\xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2})$, $(\xi_1, \xi_2) \in \{0, 1\}^2$, are given by

$$(14) \quad R_k^{(\xi_1, \xi_2)} = \frac{1}{2} \begin{pmatrix} \gamma_{\xi_1, \xi_2}(3\tau) + \gamma_{\xi_1, \xi_2}(\tau) & \gamma_{\xi_1, \xi_2}(3\tau) - \gamma_{\xi_1, \xi_2}(\tau) \\ \gamma_{\xi_1, \xi_2}(3\tau) - \gamma_{\xi_1, \xi_2}(\tau) & \gamma_{\xi_1, \xi_2}(3\tau) + \gamma_{\xi_1, \xi_2}(\tau) \end{pmatrix} \cdot \beta_{\widehat{k}}^{(0 \ 0 \ 0 \ 0)},$$

we first simplify the right-hand side by

$$(17) \quad \begin{aligned} \varphi_{\xi_1, \xi_2}^\sigma(k, x) &= \begin{pmatrix} e^{i\langle k + \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, x \rangle_2} \\ \sigma e^{i\langle k + \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, x + \tau \rangle_2} \end{pmatrix} \\ &= e^{i\langle \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, x \rangle_2} \begin{pmatrix} e^{i\langle k, x \rangle_2} \\ \sigma \gamma_{\xi_1, \xi_2}(\tau) e^{i\langle k, x + \tau \rangle_2} \end{pmatrix}, \quad \sigma \in \{+, -\}. \end{aligned}$$

For $x + \tau \in \mathbb{L}_T^{(\zeta_1, \zeta_2)}$, $(\zeta_1, \zeta_2) \in \{0, 1\}^2$ we further obtain due to $x = 2j_1 a_1 + 2j_2 a_2$

$$e^{i\langle \xi_1 \frac{b_1}{2} + \xi_2 \frac{b_2}{2}, x \rangle_2} = (-1)^{\zeta_1 \xi_1 + \zeta_2 \xi_2}.$$

Now consider the left hand-side of (16) in terms of the splitting of \mathbb{L}_T , i.e.,

$$(P\varphi_c^\pm)(k, x), \quad x + \tau \in \mathbb{L}_T^{(\zeta_1, \zeta_2)}, \quad (\zeta_1, \zeta_2) \in \{0, 1\}^2.$$

For $x + \tau \in \mathbb{L}_T^{(0,0)}$ we have $x \in \mathbb{L}_G^{(1,1)}$ according to (11) (i.e., \odot/\blacklozenge in Figures 10 and 11). The application of the interpolation rule then yields,

$$(18) \quad \begin{aligned} (P\varphi_c^\pm)(k, x) &= \begin{pmatrix} w_s (e^{i\langle k, x + a_1 - a_2 \rangle_2} + e^{i\langle k, x - a_1 + a_2 \rangle_2}) \\ \pm \frac{1}{2} e^{i\langle k, x + \tau \rangle_2} \end{pmatrix} \\ &+ \begin{pmatrix} w_\ell (e^{i\langle k, x + a_1 + a_2 \rangle_2} + e^{i\langle k, x - a_1 - a_2 \rangle_2}) \\ \pm \frac{1}{2} e^{i\langle k, x + \tau \rangle_2} \end{pmatrix} \\ &= \begin{pmatrix} 2[w_s \cos(\langle k, a_1 - a_2 \rangle_2) + w_\ell \cos(\langle k, a_1 + a_2 \rangle_2)] e^{i\langle k, x \rangle_2} \\ \pm e^{i\langle k, x + \tau \rangle_2} \end{pmatrix}. \end{aligned}$$

For $x + \tau \in \mathbb{L}_T^{(0,1)}$ we have $x \in \mathbb{L}_G^{(1,0)}$ ($\blacktriangleleft/\blacklozenge$) and thus,

$$(19) \quad \begin{aligned} (P\varphi_c^\pm)(k, x) &= \begin{pmatrix} w_s (e^{i\langle k, x + a_1 \rangle_2} + e^{i\langle k, x - a_1 \rangle_2}) \\ \pm w_s (e^{i\langle k, x + \tau + a_2 \rangle_2} + e^{i\langle k, x + \tau - a_2 \rangle_2}) \end{pmatrix} \\ &+ \begin{pmatrix} w_\ell (e^{i\langle k, x + a_1 - 2a_2 \rangle_2} + e^{i\langle k, x - a_1 + 2a_2 \rangle_2}) \\ \pm w_\ell (e^{i\langle k, x + \tau + 2a_1 - a_2 \rangle_2} + e^{i\langle k, x + \tau - 2a_1 + a_2 \rangle_2}) \end{pmatrix} \\ &= \begin{pmatrix} 2[w_s \cos(\langle k, a_1 \rangle_2) + w_\ell \cos(\langle k, a_1 - 2a_2 \rangle_2)] e^{i\langle k, x \rangle_2} \\ \pm 2[w_s \cos(\langle k, a_2 \rangle_2) + w_\ell \cos(\langle k, 2a_1 - a_2 \rangle_2)] e^{i\langle k, x + \tau \rangle_2} \end{pmatrix}. \end{aligned}$$

Analogously we find for $x + \tau \in \mathbb{L}_T^{(0,1)}$ and $x \in \mathbb{L}_G^{(1,0)}$ ($\blacklozenge/\blacktriangleright$),

$$(20) \quad (P\varphi_c^\pm)(k, x) = \begin{pmatrix} 2[w_s \cos(\langle k, a_2 \rangle_2) + w_\ell \cos(\langle k, 2a_1 - a_2 \rangle_2)] e^{i\langle k, x \rangle_2} \\ \pm 2[w_s \cos(\langle k, a_1 \rangle_2) + w_\ell \cos(\langle k, a_1 - 2a_2 \rangle_2)] e^{i\langle k, x + \tau \rangle_2} \end{pmatrix}.$$

Finally we obtain for $x + \tau \in \mathbb{L}_T^{(1,1)}$ and $x \in \mathbb{L}_G^{(0,0)}$ (\blacklozenge/\odot) that,

$$(21) \quad (P\varphi_c^\pm)(k, x) = \begin{pmatrix} e^{i\langle k, x \rangle_2} \\ \pm 2[w_s \cos(\langle k, a_1 - a_2 \rangle_2) + w_\ell \cos(\langle k, a_1 + a_2 \rangle_2)] e^{i\langle k, x + \tau \rangle_2} \end{pmatrix}.$$

Using the short-hand notation

$$\begin{aligned} \beta_k^{(0,0)} &= 1, \\ \beta_k^{(0,1)} &= 2[w_s \cos(\langle k, a_2 \rangle_2) + w_\ell \cos(\langle k, 2a_1 - a_2 \rangle_2)], \\ \beta_k^{(1,0)} &= 2[w_s \cos(\langle k, a_1 \rangle_2) + w_\ell \cos(\langle k, a_1 - 2a_2 \rangle_2)], \\ \beta_k^{(1,1)} &= 2[w_s \cos(\langle k, a_1 - a_2 \rangle_2) + w_\ell \cos(\langle k, a_1 + a_2 \rangle_2)], \end{aligned}$$

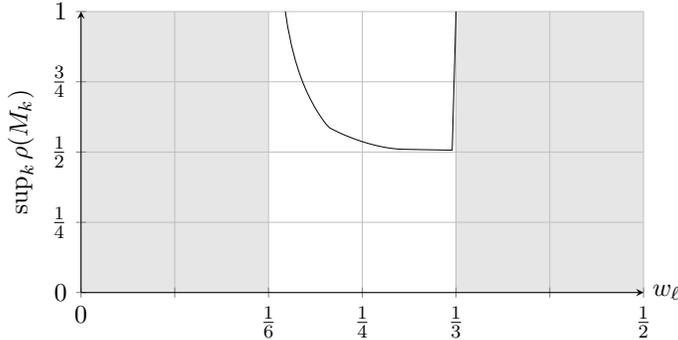


Figure 14: Plot of the estimated convergence rate of the two grid operator M using the interpolation weights w_ℓ and $w_s = 2w_\ell - 1$.

robustness and efficiency of the presented two-grid method to solve the maximally indefinite system arising in the tight-binding formulation of graphene.

5. Numerical results. In order to illustrate the findings in [section 4](#) we consider a series of numerical tests. First, we show that asymptotically for $n, m, \ell \rightarrow \infty$ the theoretical bound is sharp for the range of interpolation weights, which was declared sensible. Second, we show that the performance of the method does neither depend on the aspect ratio of $\mathbb{G}_{n,m,\ell}$ nor on its chiral angle θ . We show that the recursive application of the construction yields a scalable multigrid method with convergence rate close to the two grid rate. Finally, we show results for non-periodic boundary conditions and discuss the difficulties that arise.

Two grid. We first consider the asymptotic convergence rate of the two grid method for varying interpolation weights $w_\ell \in (\frac{1}{6}, \frac{1}{3})$ and increasing lattice sizes $\mathbb{G}_{2^{k+1}, 2^{k+1}, 2^{k+1}}$ with periodic boundary conditions. As can be seen in [Figure 15](#) the actual convergence rate stays strictly below the theoretical estimate for a wide range of interpolation weights. Towards the boundaries of $(\frac{1}{6}, \frac{1}{3})$ the behavior becomes erratic and divergence sets in earlier than predicted in the theory due to numerical instabilities. As expected the theoretical bound becomes sharper for increasing lattice sizes.

In a second set of tests we report in [Figures 16](#) and [17](#) the behaviour of the two grid method with respect to changing aspect ratios and chiral angles of $\mathbb{G}_{n,m,\ell}$ by varying n, m and ℓ . In these tests the number of atoms is kept fixed at around 10^4 . While the change in chiral angle at fixed aspect ratio has no influence on the two grid convergence (cf. [Figure 17](#)), the aspect ratio affects the asymptotic convergence rate (cf. [Figure 16](#)). This directly follows from [Lemma 8](#), i.e., the change of the discrete spectrum $\Lambda_{n,m,\ell}$ with respect to n, m and ℓ .

Multigrid. Even though the developed theory only covers the two grid method, its construction is recursively applicable as the coarse grid operator is again formulated on a hexagonal lattice. In [Figure 18](#) we report results of a multigrid V -cycle on $\mathbb{G}_{2^{k+1}, 2^{k+1}, 2^{k+1}}$ for varying interpolation weights $w_\ell \in (\frac{1}{6}, \frac{1}{3})$ using k levels in the multigrid hierarchy. The result shows that the theoretical two grid convergence estimate is not a sharp bound but still a good estimate for the k level multigrid V -cycle. The stagnation of the convergence rates for $k = 7$ and $k = 9$ indicate that the approach should scale well with increasing problem size and, concurrently, number of

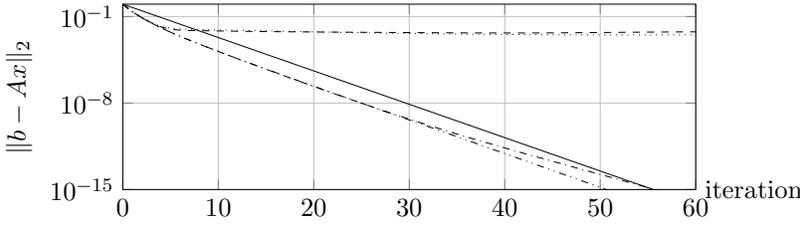


Figure 19: Convergence of the multigrid method ($w_\ell = \frac{1}{4}$ and $w_s = -\frac{1}{2}$, 5 level V-cycle) on $\mathbb{G}_{64,64,64}$ using different combinations of boundary conditions. In here (x_C, x_T) denotes the armchair b.c., x_C , and the zig-zag b.c., x_T , where p marks a periodic and o an open condition. — theor. bound, ---- (o, o) , (o, p) , -.-.- (p, o) and -.-.-.- (p, p) .

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